



LECTURE NOTES IN CONTROL
AND INFORMATION SCIENCES

296

T. Matsuo
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Realization Theory of Discrete-Time Dynamical Systems



Springer

Realization Theory Of Discretetime Dynamical Systems

Lecture Notes In Control And Information Sciences 296

Tsuyoshi Matsuo



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Realization Theory and Design of Digital Images Yasumichi Hasegawa, Tatsuo Suzuki, 2006-10-18 This monograph deals with the description and design of digital images Regarding digital images as special input output relations in our previous book with LNCIS series the description problem of digital images is transformed into the realization problem of digital images From the data in digital images mathematical models will be constructed Then new systems which describe faithfully any digital images provide new results and their extensions which design digital images As concerned with mathematical models for digital images this monograph introduces 2 Commutative Linear Representation Systems for two dimensional images and 3 Commutative Linear Representation Systems for three dimensional images This monograph is intended for researchers and graduate students who specialized in image processing and system theory Explicit Stability Conditions for Continuous Systems Michael I. Gil, 2005-03-17 Explicit Stability Conditions for Continuous Systems deals with non autonomous linear and nonlinear continuous finite dimensional systems Explicit conditions for the asymptotic absolute input to state and orbital stabilities are discussed This monograph provides new tools for specialists in control system theory and stability theory of ordinary differential equations with a special emphasis on the Aizerman problem A systematic exposition of the approach to stability analysis based on estimates for matrix valued functions is suggested and various classes of systems are investigated from a unified viewpoint **Switched and Impulsive Systems** Zhengguo Li, Yengchai Soh, Changyun Wen, 2005-02-16 In this volume the important concept of switched and impulsive control is discussed with a wide field of applications in the analysis and control of complex systems This monograph provides the reader with a comprehensive coverage of switched and impulsive systems including new original work with various applications such as switched server systems scalable video coding systems chaotic based secure communication or quality of service on the internet Switched and Impulsive Systems can be used as a reference or a text for a course at graduate level

Identification of Nonlinear Systems Using Neural Networks and Polynomial Models Andrzej Janczak, 2004-11-18 This monograph systematically presents the existing identification methods of nonlinear systems using the block oriented approach It surveys various known approaches to the identification of Wiener and Hammerstein systems which are applicable to both neural network and polynomial models The book gives a comparative study of their gradient approximation accuracy computational complexity and convergence rates and furthermore presents some new and original methods concerning the model parameter adjusting with gradient based techniques Identification of Nonlinear Systems Using Neural Networks and Polynomial Models is useful for researchers engineers and graduate students in nonlinear systems and neural network theory Hybrid Estimation of Complex Systems Michael W. Hofbaur, 2005-06-09 This monograph provides a tool set for hybrid estimation that can successfully monitor the behavior of complex artifacts with a large number of possible operational and failure modes such as production plants automotive or aeronautic systems and autonomous robots For this

purpose ideas from the fields of System Theory and Artificial Intelligence are taken and hybrid estimation is reformulated as a search problem This allows to focus the estimation onto highly probably operational modes without missing symptoms that might be hidden among the noise in the system Additionally a novel approach to continue hybrid estimation in the presence of unknown behavioral modes and to automate system analysis and synthesis tasks for on line operation are presented This leads to a flexible model based hybrid estimation scheme for complex artifacts that robustly copes with unforeseen situations

H-infinity Control and Estimation of State-multiplicative Linear Systems Eli Gershon, Uri Shaked, Isaac Yaesh, 2005-06-24 Multiplicative noise appears in systems where the process or measurement noise levels depend on the system state vector Such systems are relevant for example in radar measurements where larger ranges involve higher noise level This monograph embodies a comprehensive survey of the relevant literature with basic problems being formulated and solved by applying various techniques including game theory linear matrix inequalities and Lyapunov parameter dependent functions Topics covered include convex H_2 and H_∞ norms analysis of systems with multiplicative noise state feedback control and state estimation of systems with multiplicative noise dynamic and static output feedback of stochastic bilinear systems tracking controllers for stochastic bilinear systems utilizing preview information Various examples which demonstrate the applicability of the theory to practical control engineering problems are considered two such examples are taken from the aerospace and guidance control areas

Perturbation Compensator based Robust Tracking Control and State Estimation of Mechanical Systems SangJoo Kwon, Wan Kyun Chung, 2004-07-07 This monograph investigates a practical way to achieve robust motion control and state estimation Kalman filtering of mechanical systems which is a promising approach in terms of the perturbation compensator The book presents novel approaches for design and analysis of perturbation observers as well as an extension to robust motion control and robust state estimation The book is written in a self contained manner including experimental results in each chapter clearly validating the developed theories

Sound Capture for Human / Machine Interfaces Wolfgang Herbordt, 2005-03-22 With a continuously increasing desire for natural and comfortable human machine interaction the acoustic interface of any terminal for multimedia or telecommunication services is challenged to allow seamless and hands free audio communication Sound Capture for Human Machine Interfaces introduces the practical aspects of microphone array signal processing and presents various combinations of beamforming and acoustic echo cancellation

American Book Publishing Record ,2004

Realization Theory of Discrete-Time Dynamical Systems Tsuyoshi Matsuo, Yasumichi Hasegawa, 2003-10-08 This monograph extends Realization Theory to the discrete time domain It includes new results and constructs a new and very wide inclusion relation for various non linear dynamical systems After establishing some features of discrete time dynamical systems it presents results concerning systems which are proposed by the authors for the first time They introduce General Dynamical Systems Linear Representation Systems Affine Dynamical Systems Pseudo Linear Systems Almost Linear Systems and So called Linear Systems for discrete time and demonstrate the

relationship between them and the other dynamical systems This book is intended for graduate students and researchers who study control theory *Positive Systems* ,2006 *Mathematical Reviews* ,2005 *Subject Catalog* Library of Congress,1982 *Instrumental Variable Methods for System Identification* T. Söderström,P.G. Stoica,1983-09 [Subject Catalog, 1982](#) Library of Congress,1982 **Forthcoming Books** Rose Arny,2003 *Subject Guide to Books in Print* ,1996

Realization Theory of Continuous-time Dynamical Systems Tsuyoshi Matsuo,1981 In this monograph I shall present a basis of realization theory of dynamical system Realization problem is to determine an intrinsic mathematical model canonical dynamical system from the input output relations of a given causal black box i e to understand fully the internal behavior of the black box from the experimental data of it Moreover if possible we want to make the mathematical model real Realization theory was mainly developed in the field of discrete time linear systems as the algebraic system theory On the other hand it has been recognized that the highly developed automata theory has close relations with realization theory However there exist serious gaps between discrete time linear systems and automata for example the way of action of inputs on states are quite different In continuous time linear system the situation is worse There is no established way to think what is the set of input functions which act on states [Index of Mathematical Papers](#) ,1985 **Control Problems of**

Discrete-Time Dynamical Systems Yasumichi Hasegawa,2013-11-18 This monograph deals with control problems of discrete time dynamical systems which include linear and nonlinear input output relations It will be of popular interest to researchers engineers and graduate students who specialized in system theory A new method which produces manipulated inputs is presented in the sense of state control and output control This monograph provides new results and their extensions which can also be more applicable for nonlinear dynamical systems To present the effectiveness of the method many numerical examples of control problems are provided as well

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