Tan Kok Kiong Lee Tong Heng Huang Sunan





Precision Motion Control

Design and Implementation 2nd Edition



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Precision Motion Control Design And Implementation

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Precision Motion Control Design And Implementation:

Precision Motion Control Kok Kiong Tan, Tong Heng Lee, Sunan Huang, 2007-11-29 Precision Motion Control focuses on enabling technologies for precision engineering issues of direct importance to be addressed in the overall system design and realization precision instrumentation and measurement geometrical calibration and compensation and motion control It is a compilation of the most important results and publications from a major project that develops a state of the art high speed ultra precision robotic system The second edition has been edited and rewritten throughout with the following particular areas being expanded or added piezoelectric actuators fine movement control gantry stage control interpolation of quadrature encoder signals geometrical error modelling for single dual and general XY axis stages By providing detailed experimental verifications of the material developed a comprehensive and thorough treatment of the subject matter accessible to a broad base of readers ranging from academics to practitioners is provided **Precision Motion Control** Kok K. Tan, Tong H. Lee, Huifang Dou, Sunan Huang, 2013-04-17 Precision manufacturing is a development that has been gathering momentum over the last century and accelerating over the last 25 years in terms of research development and application to product innovation The driving force in this development arises from requirements for much higher performance of products higher reliability longer life lower cost and miniaturization This development is widely known as precision engineering and today it is generally defined as manufacturing to tolerances which are better than one part in 105 Applications are abound and can be found in various semiconductor processes e.g. lithography wafer probing inspection Coordinate Measuring Machines CMMs and precision metrology systems e g Scanning Probe Microscopy SPM and robot machine tools to carry out micro assembly e g MEMS and delicate short wavelength laser processes As an enabling technology for precision engineering precision instrumentation and measurement geometrical calibration and compensation and motion control are directly important issues to be addressed in the overall system design and realization This book is focused on these aspects of precision engineering It is a compilation of the major results and publications from a major project which develop a state of the art high speed ultra precision robotic system A comprehensive and thorough treatment of the subject matter is provided in a manner that is amenable to a broad base of readers ranging from the academics to the practitioners by providing detailed experimental verifications of the developed materials **Advanced Optimization for** Motion Control Systems Jun Ma, Xiaocong Li, Kok Kiong Tan, 2020-01-24 Precision motion control is strongly required in many fields such as precision engineering micromanufacturing biotechnology and nanotechnology Although great achievements have been made in control engineering it is still challenging to fulfill the desired performance for precision motion control systems Substantial works have been presented to reveal an increasing trend to apply optimization approaches in precision engineering to obtain the control system parameters. In this book we present a result of several years of work in the area of advanced optimization for motion control systems The book is organized into two parts Part I focuses

on the model based approaches and Part II presents the data based approaches To illustrate the practical appeal of the proposed optimization techniques theoretical results are verified with practical examples in each chapter Industrial problems explored in the book are formulated systematically with necessary analysis of the control system synthesis By virtue of the design and implementation nature this book can be used as a reference for engineers researchers and students who want to utilize control theories to solve the practical control problems As the methodologies have extensive applicability in many control engineering problems the research results in the field of optimization can be applied to full fledged industrial processes filling in the gap between research and application to achieve a technology frontier increment Automation Technology Development Bo Zhao, Guang Lin Wang, Wei Ma, Zhibo Yang, Yan Yan, 2010-12-30 Selected peer reviewed papers from the 14th Conference of China University Society on Manufacturing Automation August 11 14 2010 Iiaozuo China Deutsche Nationalbibliographie und Bibliographie der im Ausland erschienenen deutschsprachigen Veröffentlichungen ,2001 Motion Control Federico Casolo, 2010-01-01 The book reveals many different aspects of motion control and a wide multiplicity of approaches to the problem as well Despite the number of examples however this volume is not meant to be exhaustive it intends to offer some original insights for all researchers who will hopefully make their experience available for a forthcoming publication on the subject **Advances In Variable** Structure Systems: Analysis, Integration And Application - Proceedings Of The 6th Ieee International Workshop **On Variable Structure Systems** Jian-xin Xu, Xing Huo Yu, 2000-11-14 The last of such a workshop in the 20th Century this workshop aims not only to summarize the state of the art developments in VSS theory and applications but also identify new promising directions perceived as being important for VSS in the 21st century The 20th Century has witnessed the formation and consolidation of VSS theory and its applications It has also witnessed an emerging trend of cross fertilization and integration of VSS with other control and non control areas such as feedback linearization flatness passivity based control adaptive control system identification pulse width modulation Hinf geometric and algebraic methods artificial intelligence modelling and optimisation neural networks fuzzy logic etc This trend will continue and flourish in the new millennium Special features of the book include a survey paper entitled VSS Premise of XX Century Evidences of a Witness by the father of VSS theory Professor Vadim Utkin and other articles by many authoritative experts in VSS Intelligent Robotics and Applications YongAn Huang, Hao Wu, Honghai Liu, Zhouping Yin, 2017-08-04 The three volume set LNAI 10462 LNAI 10463 and LNAI 10464 constitutes the refereed proceedings of the 10th International Conference on Intelligent Robotics and Applications ICIRA 2017 held in Wuhan China in August 2017 The 235 papers presented in the three volumes were carefully reviewed and selected from 310 submissions. The papers in this third volume of the set are organized in topical sections on sensors and actuators mobile robotics and path planning virtual reality and artificial intelligence aerial and space robotics mechatronics and intelligent manufacturing Advances in Engineering Research and Application Kai-Uwe Sattler, Duy

Cuong Nguyen, Ngoc Pi Vu, Banh Tien Long, Horst Puta, 2020-11-23 This proceedings book features volumes gathered selected contributions from the International Conference on Engineering Research and Applications ICERA 2020 organized at Thai Nguyen University of Technology on December 1 2 2020 The conference focused on the original researches in a broad range of areas such as Mechanical Engineering Materials and Mechanics of Materials Mechatronics and Micromechatronics Automotive Engineering Electrical and Electronics Engineering and Information and Communication Technology Therefore the book provides the research community with authoritative reports on developments in the most exciting areas in these fields Proceedings of the Ninth Symposium, 1984 **Proceedings of the ... Annual Conference of the IEEE Industrial Electronics Society** IEEE Industrial Electronics Society. Conference, 2004 **Advanced Optimization for** Motion Control Systems Jun Ma, Xiaocong Li, Kok Kiong Tan, 2020-02-19 Precision motion control is strongly required in many fields such as precision engineering micromanufacturing biotechnology and nanotechnology Although great achievements have been made in control engineering it is still challenging to fulfill the desired performance for precision motion control systems Substantial works have been presented to reveal an increasing trend to apply optimization approaches in precision engineering to obtain the control system parameters. In this book we present a result of several years of work in the area of advanced optimization for motion control systems. The book is organized into two parts Part I focuses on the model based approaches and Part II presents the data based approaches To illustrate the practical appeal of the proposed optimization techniques theoretical results are verified with practical examples in each chapter Industrial problems explored in the book are formulated systematically with necessary analysis of the control system synthesis By virtue of the design and implementation nature this book can be used as a reference for engineers researchers and students who want to utilize control theories to solve the practical control problems As the methodologies have extensive applicability in many control engineering problems the research results in the field of optimization can be applied to full fledged industrial processes filling in the gap between research and application to achieve a technology frontier increment Final Design Power Transmission Design ,1996 Mechatronics, Robotics and Automation Yun Hae **Documentation**,2000 Kim, 2013-08-30 Selected peer reviewed papers from the 2013 International Conference on Mechatronics Robotics and Automation ICMRA 2013 June 13 14 2013 Guangzhou China Linear Controller Design Stephen P. Boyd, Craig H. Who's who in Technology Louann Chaudier, 1986 **High Performance Machine Tool Controllers** Barratt, 1991 Mohammed Ibrahim Al-Majed, 1997 **Astrodynamics 1995** ,1996 The British National Bibliography Arthur James Wells,2001

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