



# Robot Learning

**Brian Carrigan**



## **Robot Learning:**

**Robot Learning** J. H. Connell, Sridhar Mahadevan, 2012-12-06 Building a robot that learns to perform a task has been acknowledged as one of the major challenges facing artificial intelligence. Self-improving robots would relieve humans from much of the drudgery of programming and would potentially allow operation in environments that were changeable or only partially known. Progress towards this goal would also make fundamental contributions to artificial intelligence by furthering our understanding of how to successfully integrate disparate abilities such as perception, planning, learning, and action. Although its roots can be traced back to the late fifties, the area of robot learning has lately seen a resurgence of interest. The flurry of interest in robot learning has partly been fueled by exciting new work in the areas of reinforcement learning, behavior-based architectures, genetic algorithms, neural networks, and the study of artificial life. Robot Learning gives an overview of some of the current research projects in robot learning being carried out at leading universities and research laboratories in the United States. The main research directions in robot learning covered in this book include reinforcement learning, behavior-based architectures, neural networks, map learning, action models, navigation, and guided exploration.

Recent Advances in Robot Learning Judy A. Franklin, Tom M. Mitchell, Sebastian Thrun, 2012-12-06 Recent Advances in Robot Learning contains seven papers on robot learning written by leading researchers in the field. As the selection of papers illustrates, the field of robot learning is both active and diverse. A variety of machine learning methods ranging from inductive logic programming to reinforcement learning is being applied to many subproblems in robot perception and control, often with objectives as diverse as parameter calibration and concept formulation. While no unified robot learning framework has yet emerged to cover the variety of problems and approaches described in these papers and other publications, a clear set of shared issues underlies many robot learning problems. Machine learning when applied to robotics is situated; it is embedded into a real-world system that tightly integrates perception, decision making, and execution. Since robot learning involves decision making, there is an inherent active learning issue. Robotic domains are usually complex, yet the expense of using actual robotic hardware often prohibits the collection of large amounts of training data. Most robotic systems are real-time systems. Decisions must be made within critical or practical time constraints. These characteristics present challenges and constraints to the learning system. Since these characteristics are shared by other important real-world application domains, robotics is a highly attractive area for research on machine learning. On the other hand, machine learning is also highly attractive to robotics. There is a great variety of open problems in robotics that defy a static, hand-coded solution. Recent Advances in Robot Learning is an edited volume of peer-reviewed original research comprising seven invited contributions by leading researchers. This research work has also been published as a special issue of Machine Learning, Volume 23, Numbers 2 and 3.

**Using Educational Robots to Enhance Learning** Dejian Liu, Ronghuai Huang, Ying Chen, Michael Agyemang Adarkwah, Xiangling Zhang, Xin Li, Junjie Zhang, Ting Da, 2024-09-28 This book presents advances in the research of

educational robotics and showcases how they can be used to facilitate learning It summarizes popular and relevant terms and theories in educational robotics via analyzing one hundred influential journal articles in this field to provide readers background knowledge on the subject matter This book also guides readers in understanding how different types of robotics are utilized to promote learning among different types of students in different contexts and in different disciplines of study

**Robots** Brian Carrigan,1980      *Machine Learning* Claude Sammut,Achim Günther Hoffmann,Achim Hoffmann,2002

**IROS** ,1992      **Interdisciplinary Approaches To Robot Learning** Andreas Birk,Yiannis Demiris,2000-06-12 Robots are being used in increasingly complicated and demanding tasks often in environments that are complex or even hostile Underwater space and volcano exploration are just some of the activities that robots are taking part in mainly because the environments that are being explored are dangerous for humans Robots can also inhabit dynamic environments for example to operate among humans not just in factories but also taking on more active roles Recently for instance they have made their way into the home entertainment market Given the variety of situations that robots will be placed in learning becomes increasingly important Robot learning is essentially about equipping robots with the capacity to improve their behaviour over time based on their incoming experiences The papers in this volume present a variety of techniques Each paper provides a mini introduction to a subfield of robot learning Some also give a fine introduction to the field of robot learning as a whole There is one unifying aspect to the work reported in the book namely its interdisciplinary nature especially in the combination of robotics computer science and biology This approach has two important benefits first the study of learning in biological systems can provide robot learning scientists and engineers with valuable insights into learning mechanisms of proven functionality and versatility second computational models of learning in biological systems and their implementation in simulated agents and robots can provide researchers of biological systems with a powerful platform for the development and testing of learning theories      *Advanced Robotics* ,1997      *Robot Learning by Visual Observation* Aleksandar Vakanski,Farrokh Janabi-Sharifi,2017-01-13 This book presents programming by demonstration for robot learning from observations with a focus on the trajectory level of task abstraction Discusses methods for optimization of task reproduction such as reformulation of task planning as a constrained optimization problem Focuses on regression approaches such as Gaussian mixture regression spline regression and locally weighted regression Concentrates on the use of vision sensors for capturing motions and actions during task demonstration by a human task expert      **AAAI-91** American Association for Artificial Intelligence,1991 AAAI proceedings describe innovative concepts techniques perspectives and observations that present promising research directions in artificial intelligence July 15 19 1991 Anaheim California Topics include Communication and Cooperation AI and Education User Interfaces Natural Language Distributed AI Reasoning about Physical Systems Perception Planning and Robotics Machine Learning      *Robotics* Rex Maus,Randall Allsup,1986 Covering uses of robotics in all phases of manufacturing at a technical level especially for managers who are not engineers or

computer trained this book contains case studies from major geographic business sectors and features definitions and glossary of major buzzwords and acronyms used in the field Also included is an extensive bibliography of sources

**Bayesian Inference and Maximum Entropy Methods in Science and Engineering** Marcelo de Souza Laurretto, Carlos A. de Bragança Pereira, Julio Michael Stern, 2008-12-04 The MaxEnt2008 28th International Workshop on Bayesian Inference and Maximum Entropy Methods in Science and Engineering encompassed all aspects of information theory probability statistical inference and statistical physics including research on foundations and theoretical developments as well as modeling techniques for several specific application areas AAAI 99 American Association for Artificial Intelligence, 1999 AAAI proceedings describe innovative concepts techniques perspectives and observations that present promising research directions in artificial intelligence The annual AAAI National Conference and Innovative Applications of Artificial Intelligence Conference provide a forum for information exchange and interaction among researchers from all disciplines of AI Contributions include theoretical experimental and empirical results The technical papers published in this proceedings were selected by a rigorous double blind review process The National Conference papers cover a myriad of topics including agents artificial intelligence and the world wide web cognitive systems constraint satisfaction problems knowledge acquisition knowledge representation learning model based reasoning natural language and information retrieval planning robotics satisfiability scheduling search tractable reasoning and vision The Innovative Applications Conference papers feature deployed and emerging applications These papers will be of special benefit to AI applications developers In addition abstracts from the Invited talks Intelligent Systems Demonstrations Robotic Competition and Exhibition SIGART AAAI Doctoral Consortium and Student programs are also included in this proceedings **Space Station Automation IV** Wun C. Chiou, 1988 **Sensor Fusion and Decentralized Control in Robotic Systems** ,1998 Advances in Artificial Intelligence Canadian Society for Computational Studies of Intelligence. Conference, 1996 *Robot Sensors* Alan Pugh, 1986 V 1 Vision v 2 Tactile and non vision **Proceedings 2003 IEEE/RSJ International Conference on Intelligent Robots and Systems** ,2003 **Applications of Industrial Robots** ,1987 Compilation of selected papers on the use of industrial robots Case-based Reasoning Research and Development ,1997

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