

Robotic Kinematics:
Symbolic Automation and
Numerical Synthesis
(Computer Science and
Computer Engineering
Series)

Ho, C.Y.

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Robot Kinematics Symbolic Automation And Numerical Synthesis

**F. C. A. Groen, Shigeo Hirose, Charles E.
Thorpe**



Robot Kinematics Symbolic Automation And Numerical Synthesis:

Robot Kinematics Chung You Ho, Jen Sriwattanathamma, 1990 This volume is a unified treatment of the field of robot kinematics based upon symbolic automation and numerical synthesis approaches It focuses on visualizing the robot kinematic mechanisms formulating suitable mathematical models for analyzing the behaviour of industrial manipulators and deriving efficient algorithms for obtaining the solutions *Symbolic Automation and Numerical Synthesis for Robot Kinematics* Jen Sriwattanathamma, 1988 **Computer-Aided Design, Engineering, and Manufacturing** Cornelius T.

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Dissertations, 1988 **NC Verification for a Wire-cut Electric Discharge Machine** Gary Tom Lee, 1992 **The Cumulative Book Index**, 1991 A world list of books in the English language **Mathematical Foundations of Computer Science 2013** Krishnendu Chatterjee, Jiri Sgall, 2013-08-16 This book constitutes the thoroughly refereed conference proceedings of the 38th International Symposium on Mathematical Foundations of Computer Science MFCS 2013 held in Klosterneuburg Austria in August 2013 The 67 revised full papers presented together with six invited talks were carefully selected from 191 submissions Topics covered include algorithmic game theory algorithmic learning theory algorithms and data structures automata formal languages bioinformatics complexity computational geometry computer assisted reasoning concurrency theory databases and knowledge based systems foundations of computing logic in computer science models of

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